PW #1: 1st-order ordinary differential equations

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We are interested in comparing different numerical schemes to solve 1st-order ODEs from an engineer point of view. Hence we shall focus on accuracy and efficiency.

1 Linear ODEs

We first consider a linear case over the time interval [0, 1]:

$$\begin{cases} y'(t) = 3y(t) - 1, \\ y(0) = y_0. \end{cases}$$
 (1)

Constant y_0 is assumed to be known.

1. Recall the exact solution to the Cauchy problem (1) – to do so, you can multiply the equation by e^{-3t} and integrate. In particular, what is the solution for $y_0 = \frac{1}{3}$?

2. Euler schemes

- (a) Apply the explicit Euler scheme to Eq. (1). Solve the resulting difference equation.
- (b) Given a homogeneous discretization of [0,1] $t_n = n\Delta t$ for some $\Delta t > 0$, implement the resolution of (1) according to the aforementioned scheme.
- (c) Redo the same process for the implicit Euler scheme. Is any time step Δt admissible?
- (d) Show on the same plot the exact solution and the solutions obtained by means of the 2 Euler schemes for $\Delta t = 0.2, 0.1, 0.01$.

3. Higher order schemes

- (a) Apply the enhanced Euler scheme and the Crank-Nicolson scheme to Eq. (1) and solve the difference equations.
- (b) Implement these two schemes as well as the RK3 schemes and compare the numerical solutions (for $\Delta t = 0.2, 0.1, 0.01$) to the exact solution.

4. Comparisons

- (a) Plot the error $\max_{n} |y_n y(t_n)|$ for the 5 schemes and for $\Delta t = 0.2, 0.1, 0.05, 0.02, 0.01$.
- (b) Which scheme seems to be the most suitable one?

2 Lotka-Volterra equations

These equations model the evolution of an isolated predator-prey system (for instance rabbits and lynx):

$$\begin{cases} x'(t) = x(t)(3 - y(t)), & x(0) = 1, \\ y'(t) = y(t)(x(t) - 2), & y(0) = 2. \end{cases}$$
 (2)

We assume global-in-time existence for solutions to (2).

- 1. Determine which variable corresponds to the number of preys.
- 2. Rewrite Eqs. (2) as $\mathbf{Y}'(t) = \mathbf{F}(\mathbf{Y}(t))$, where $\mathbf{Y} = (x, y)$.
- 3. We set $H(x, y) = x 2\ln x + y 3\ln y$. H is called the *Hamiltonian* of the system. Show that for all $t \ge 0$, H(x(t), y(t)) = H(x(0), y(0)).
- 4. Implement the Heun method and the RK4 scheme to solve (2).
- 5. Plot the graph (x(t), y(t)) for $\Delta t = 0.01$ and $T_{final} = 10$.
- 6. Show the evolution of H(x(t), y(t)) with respect to t. Is this result in accordance with Question 3?
- 7. Determine the only constant solution to (2). Do you obtain numerically the expected result?

3 Chemical reactions

We consider the following system which models three coupled chemical reactions involving species E_1 , E_2 and E_3 :

$$\begin{cases} y_1' = -k_1 y_1 + k_3 y_2 y_3, & y_1(0) = 1, \\ y_2' = k_1 y_1 - k_3 y_2 y_3 - k_2 y_2^2, & y_2(0) = 0, \\ y_3' = k_2 y_2^2, & y_3(0) = 0. \end{cases}$$
(3)

We set: $k_1 = 0.04$, $k_2 = 3 \cdot 10^7$ and $k_3 = 10^4$ the velocities of reactions. y_k denotes the chemical concentration of species E_k . We assume that all components remain positive.

- 1. Rewrite Eqs. (3) as $\mathbf{Y}'(t) = \mathbf{F}(\mathbf{Y}(t))$, where $\mathbf{Y} = (y_1, y_2, y_3)$.
- 2. What are the stationary states (constant solutions).
- 3. Show that $y_1(t) + y_2(t) + y_3(t) = 1$ for any time t. Interpret this result from a physical point of view.
- 4. Write the implicit Euler scheme applied to Syst. (3). Show that no inversion algorithm is required to apply the scheme to this case.
- 5. Compare results with the RK4 scheme. What do results tend to show about species 1? species 3?